

Overview of ImageCLEF 2014

The screenshot shows the ImageCLEF website. The header is blue with the 'ImageCLEF' logo (a key) and the text 'ImageCLEF - Image Retrieval in CLEF'. Below the header is a navigation bar with 'Home' and 'ImageCLEF 2014' (with 'View' and 'Revisions' buttons). A left sidebar titled 'Navigation' lists: 'ImageCLEF 2014' (expanded), 'Robot vision', 'Image annotation', 'Liver CT annotation', and 'Domain adaptation'. The main content area has a green 'Motivation' header followed by text: 'ImageCLEF 2014 is part of the CLEF 2014 to be held in the city of Sheffield in the United Kingdom. It will organize the four main tasks to benchmark the challenging task of image annotation for a wide range of source images and annotation objective, such as'. On the right, there is a 'Tweets' section with a 'Follow' button and a tweet from 'ImageCLEF @imageclef' dated '1 Jun'.

Henning Müller
(for all organizers)

ImageCLEF history

- Started in **2003** with a photo retrieval task
 - 4 participants submitting results
- 2009 with 6 tasks and 65 participants
- **Retrieval** and **detection** (annotation) tasks in various domains (photo, medical, plants, ...)
- 2014
 - 4 tasks, LifeCLEF now an independent lab
 - Almost 200 registered participants
 - 21 groups submitted results

ImageCLEF objectives

- **Annotate** images with concepts
 - Using visual information, text, and other sensors
- **Language-independent** and **multilingual** indexing & retrieval from image collections
- **Multimodal** retrieval combining text with visual features and other sensors
- Extracting **semantic concepts** that can be used for several languages
- Evaluating **machine learning** approaches



ImageCLEF registration system

Hes·SO VALAIS WALLIS
Haute Ecole Spécialisée
de Suisse occidentale
Fachhochschule Westschweiz
University of Applied Sciences
Western Switzerland

CLEF 2014

IMAGE CLEF

logged in as: henning.mueller@hevs.ch

[My Account](#)

[Logout](#)

[Home](#)
[Subtracks](#)
[Collections](#)
[Runs](#)

[Users](#)
[Pending Signatures](#)

[ImageCLEF-Website](#)
[CLEF-Website](#)



[+ Register new user](#)

All users

All Users (1 - 10 of 242)							
Type	Groupname	E-mail	Country	signature OK			
admin	hesso	ivan.eggel@hevs.ch	Switzerland	✓	Update	Detail	
admin	MedGIFT	henning.mueller@hevs.ch	Switzerland	✓	Update	Detail	
admin	HES SO	alba.garcia@hevs.ch	Switzerland	✓	Update	Detail	
admin	xenocanto	bob@xeno-canto.org	Netherlands	✓	Update	Detail	
admin	TUWien ifs	rauber@ifs.tuwien.ac.at	Austria	✓	Update	Detail	
admin	TU Vienna	schindler@ifs.tuwien.ac.at	Austria	✓	Update	Detail	
admin	VALE	caputo@dis.uniroma1.it	Italy	✓	Update	Detail	
admin	Inria Zenith and Imedia teams	herve.goeau@inria.fr	France	✓	Update	Detail	
participant	XC	wp@xeno-canto.org	Netherlands	✓	Update	Detail	Delete
admin	UPV PRHLT	mauvilsa@upv.es	Spain	✓	Update	Detail	

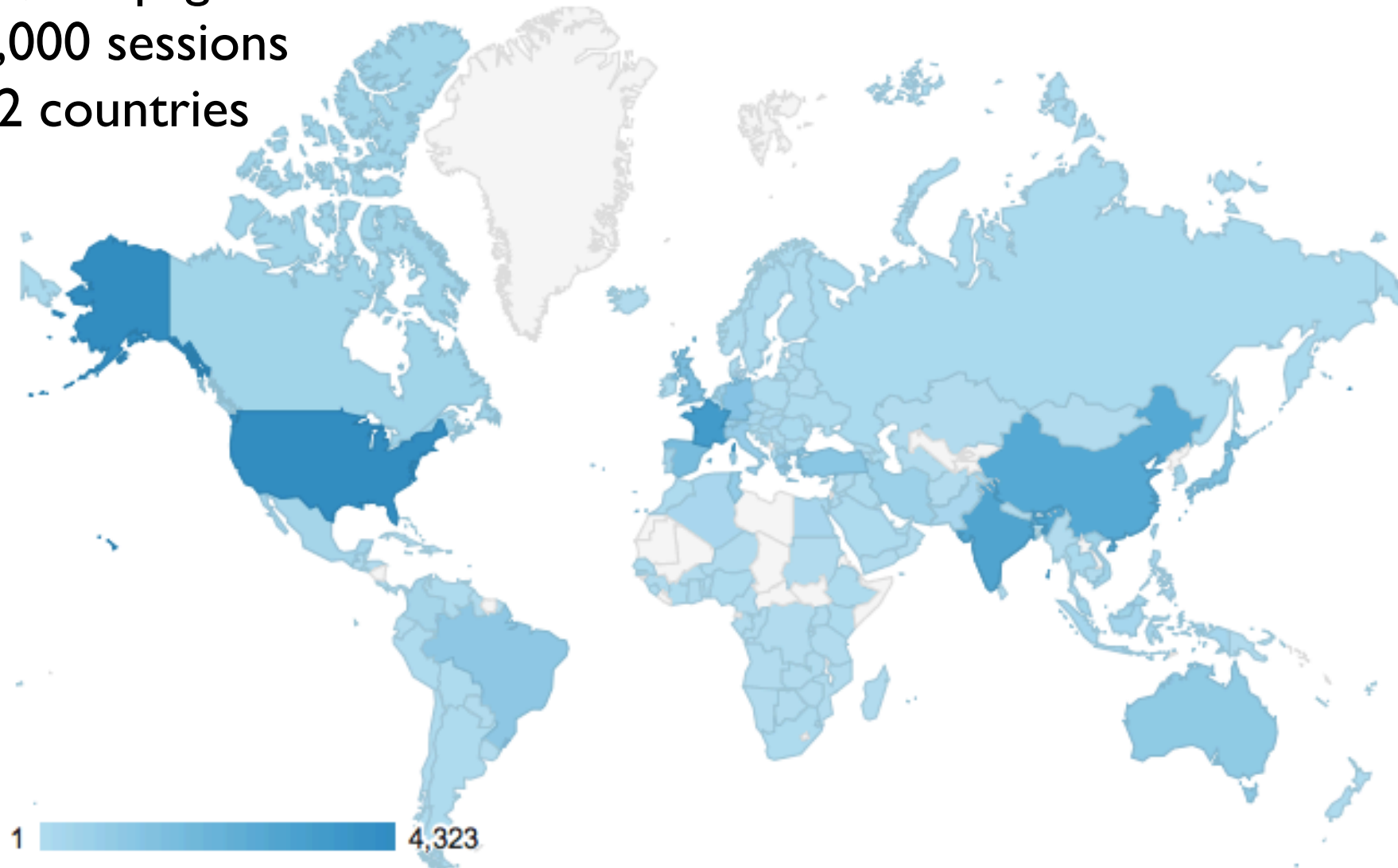
[Show Data in Single Page](#)

ImageCLEF web page

105,000 page views

37,000 sessions

162 countries



Tasks in 2014

- Scalable Concept image annotation task
 - Large-scale annotation with web data
- Robot vision task
 - Detecting places and objects in robotic images
- Domain adaptation task (new)
 - Train in one domain and evaluate in another one
- Liver annotation task (new)
 - Automatically annotate regions in the liver with semantic terms

Scalable concept image annotation task

General information

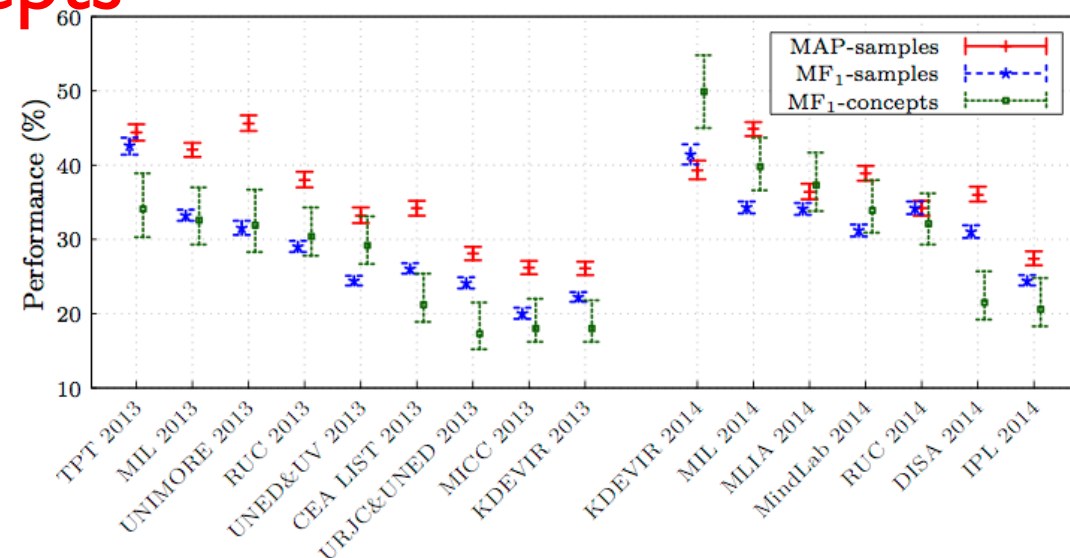
- Objective: To use automatically gathered data (web pages, language resources, etc.) to develop **scalable image annotation** systems
- Past editions: Track started in 2012, this was the third edition
- Organizers: Mauricio Villegas and Roberto Paredes (Universitat Poliècnica de València).
- **Participation**: 11 groups took part, 58 runs were submitted in total

Tasks and data

- Task description:
 - Develop and **train image annotation** systems using the provided data and/or other data as long as not hand labeled
 - Use the developed systems to **automatically annotate** a set of images for a given concept list and using as input only visual features
- Provided training data (500,000 images):
 - The original images and 7 types of extracted visual features
 - The webpages in which the images appeared and preprocessed textual features

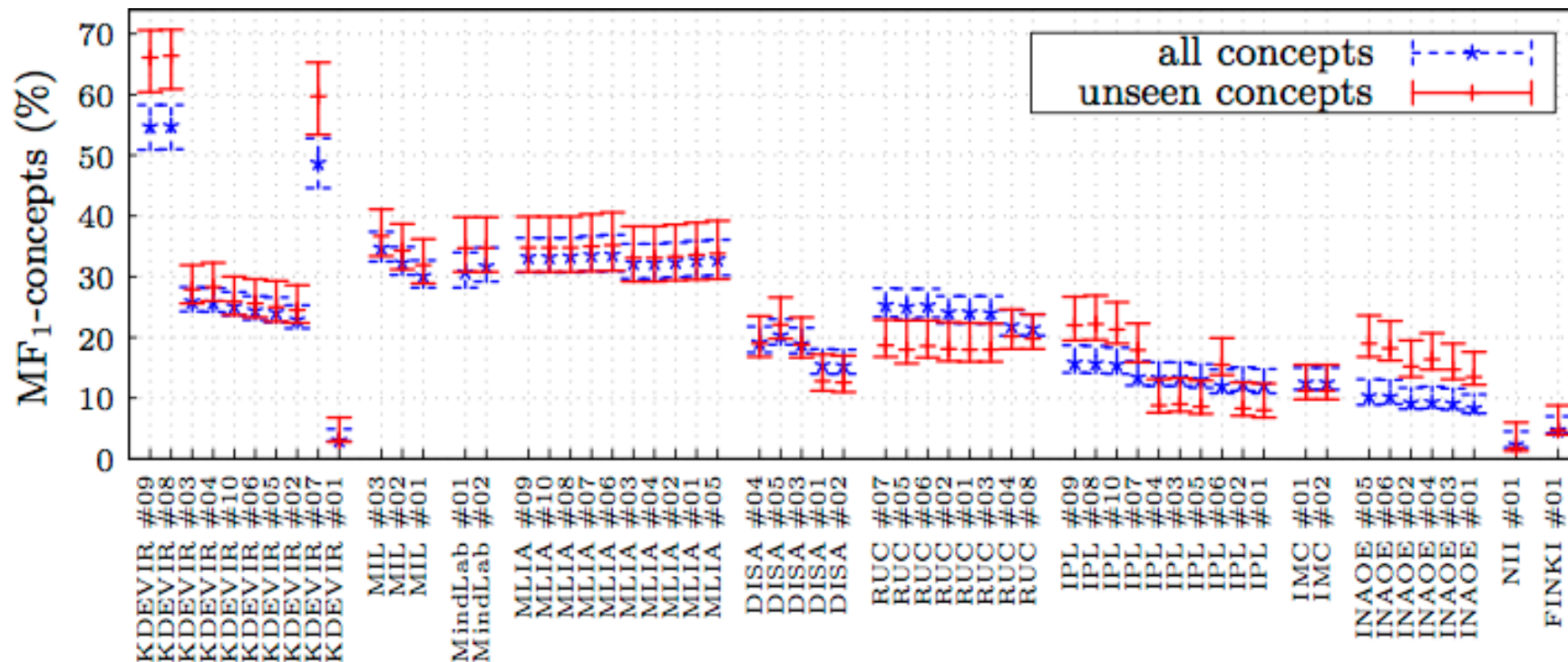
Results

- Results indicate that web data can be used for training practical and scalable annotation systems
- A **performance improvement** is observed with respect to last year's submissions
- Most improvement on MF measures, indicating better approaches for **selecting** the final **annotated concepts**



Lessons learned

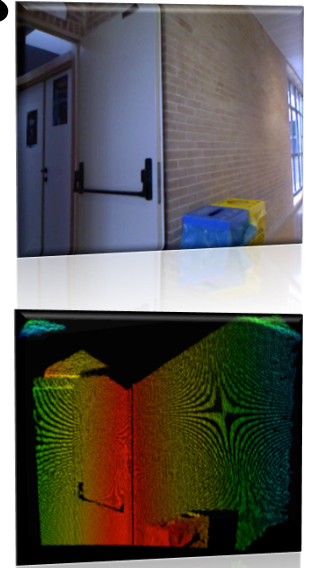
- Best system from KDEVIR group:
 - Employed provided visual features
 - Success due to classifier considering **contextual info** and usage of concept ontologies both in training and test



Robot vision task

General information

- Multimodal information retrieval
- Two problems: **place** classification and **object** recognition
 - 10 room categories, 8 objects
- Two info sources: **visual** and **depth** images
- Proposed since 2009 (5th edition)
 - Organizers: J. Martinez-Gomez, I. Garcia-Varea, M. Cazorla and V. Morell
- 4-9 participants over the years



Data and setup

- **Supervised classification** problem
 - Participants are provided with labeled sequences
 - Training (5000 frames) and validation (1500 frames)
- Each training frame contains
 - Visual Image, Range Image (.pcd format)
 - **Semantic category** of scene where frame was acquired
 - **List of objects** appearing in the scene
- Training and test sequences
 - Different building but with similar structure and objects/rooms appearance relationships



Rooms and objects

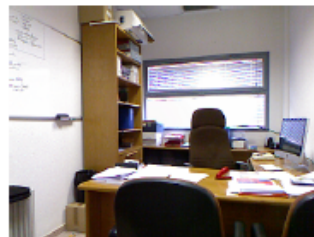
Corridor



Hall



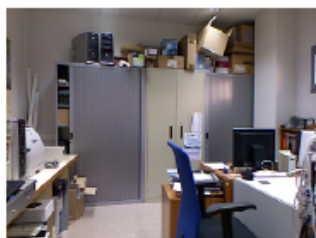
ProfessorOffice



StudentOffice



TechnicalRoom



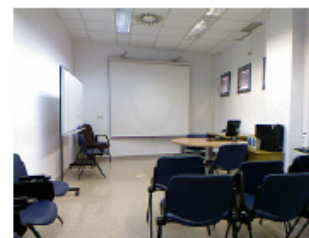
Toilet



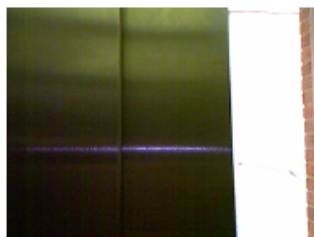
Secretary



VisioConference



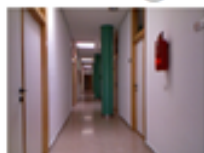
ElevatorArea



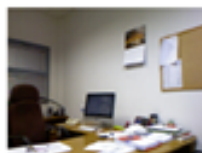
Warehouse



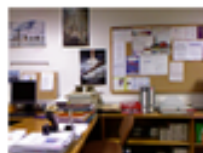
Exting.



Chair



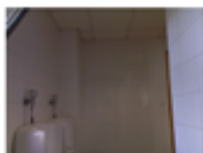
Printer



Bookshelf



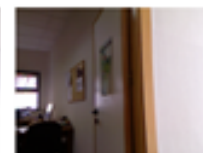
Urinal



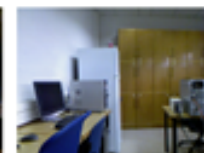
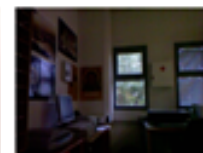
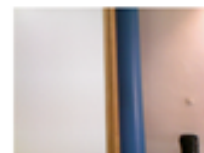
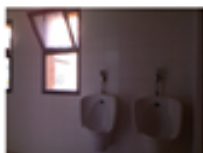
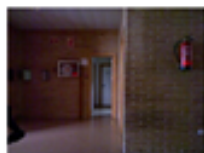
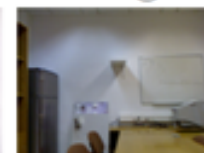
Trash



Phone



Fridge

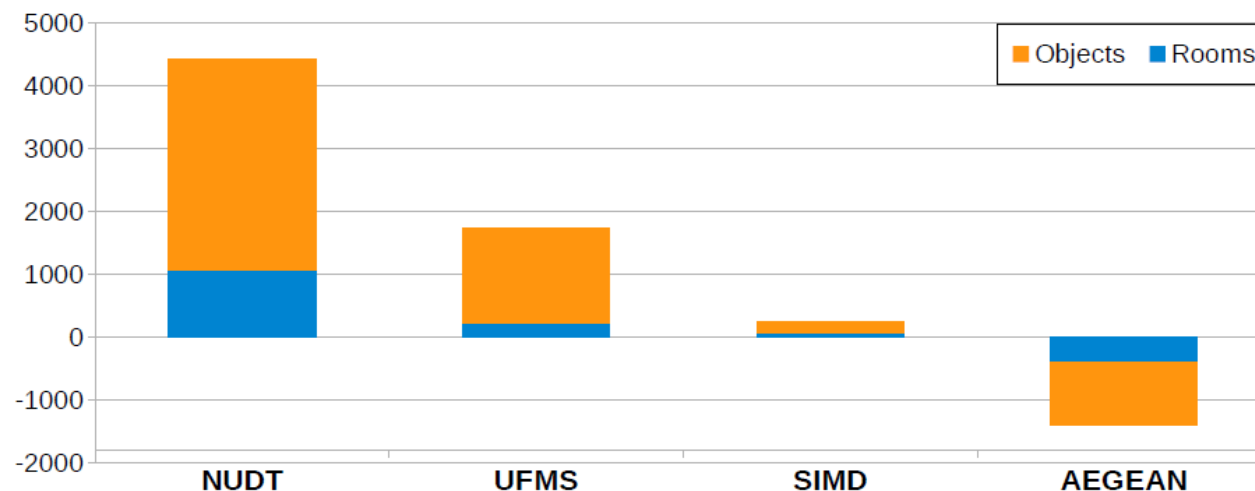


Results

- Submissions were evaluated by computing an **overall score**

Class/Room Category (one by frame)	
Correctly / Wrongly / Not Classified	+1.0 / -0.5 / 0.0 points
Object Recognition (8 by frame)	
True Positive (TP)/ FP/ TN / FN	+1.0 / -0.25 / 0.0 / -0.25 points

- Winner of the task: NUDT, Changsa, China



Domain adaptation task

Objectives and task

- Research challenge
 - How to learn object classifiers from few models learned in **another domain**



- The task
 - Learn object classifiers for 12 classes from 4 domains, use this knowledge to learn new objects in a fifth domain



Participants and runs

- Three groups submitted a total of 20 runs:
 - Xerox Research Center Europe
 - Hubert Curien Lab Group
 - Artificial Cognitive Systems Lab, Idiap Research Institute

Group Name	Score Total
XRCE	228
Hubert-Curien	158
Idiap	45

- **Easiest** class: airplane



- **Hardest** classes: bike, dog



Lessons learned

- **Ensemble Methods** rule (see talk by B. Childlovskii)
- Choice to distribute pre-computed features vs. raw images suboptimal
- 40+ groups registered, 3 groups submitted runs, 1 group submitted working notes paper
- First edition of the task and it will not be continued

Liver retrieval task

General overview

- Motivation
 - Low level visual features have a limited performance in clinical applications
 - Semantic features can work better and these can be predicted using visual features
 - This can potentially create more **complete reports** and ease **retrieval**
- Task
 - Given a cropped liver volume complete a standardized report with semantic terms in a given ontology



Data used

- 50 training and 10 test datasets
- Each training dataset is represented as:
 - A cropped 3D CT image of the liver
 - A liver mask, which defines the liver in the image
 - A ROI, which defines the lesion area in the image
 - A set of 60 CoG image descriptors of dimension 454
 - A set of 73 UsE features annotated using ONLIRA
- Test sets have the same format but UsE features are missing, goal is their prediction

Example data



Cluster size: 2
Segment: SegmentV, SegmentVI,
SegmentVII, SegmentVIII
Lobe: Right lobe
Width: 175, Height: 126
Is gallbladder adjacent? True
Is peripheral localized: False
Is sub-capsular localized: False
Is central localized: True
Margin type: Lobular
Shape: Round
Is contrasted: False
Contrast uptake: NA
Contrast pattern: NA
Lesion composition: PureCystic
Is Calcified(area): False
Area calcification type: NA
Is calcified(Capsule): NA
Capsule calcification type: NA
Is calcified(polyp): NA
Polyp calcification type: NA
Is calcified(pseudoCapsule): NA
Is calcified (Septa): NA

PseudoCapsule calcification type: NA
Is calcified(solid component): NA
Solid component calcification type: NA
Is calcified(wall): NA
Wall calcification type: NA
Density: Hypodense
Density type:
Homogeneous
Diameter type: NA
Thickness: NA
Is leveling observed: False
Leveling type: NA
Is debris observed: False
Debris location: NA
Wall type: Thin
Is Contrasted(wall): False
Is Close to vein: Right portal vein, Right hepatic
vein, Middle hepatic vein
Vasculature proximity: Bended

Results

- The **BMET** group, achieved the **best** results using an image retrieval technique
- A classifier-based method is used by the CASMIP group
- piLabVAVlab used a Generalized couple tensor factorization (GCTF) method

Grp	Comp.	Acc.	Score	Method	Feature
BMET	0.98	0.91	0.947	Image Retrieval	CoG
CASMIP	0.95	0.91	0.93	LDA + KNN	CoG+
piLabVaVlab	0.51	0.89	0.677	GCTF	CoG

Conclusions

- 2014 was a **transition** year for ImageCLEF with two totally new tasks
 - Split with LifeCLEF that has grown well
- Many groups get **access to data** but then do **not** submit runs for the competition
 - Maybe do not release the test data to all?
- Increase in performance can be seen

Contact and more information

- More information can be found at
 - <http://www.imageclef.org/>
- Contact:
 - Henning.mueller@hevs.ch