

# Image CLEF Liver CT Image Annotation Task

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- CES concept
- CaReRa project
- imageCLEF: Liver CT annotation task
- Task definition: datasets, evaluation methods
- Participants
- Results
- Conclusion



# **Clinical Experience Sharing (CES)**

- Clinical Experience Sharing (CES) refers to a searchable collective medical knowledge base that enables experience sharing among large community of medical professionals, for clinical and educational purposes.
- A CES platform would
  - <u>Empower comparative diagnosis</u> in the clinical use by presenting past cases that are relevant to a query case from a diagnostic point of view.
  - <u>Assist medical students</u> in the educational use by allowing them to browse past cases with similar/dissimilar symptoms and clinical observation but dissimilar/similar diagnoses.
- A CES platform can <u>be implemented in the form of a Content-Based</u> Case Retrieval (CBCR) system.



## CaReRa: Case Retrieval in Radiology

- CaReRa is a prototype CBCR implementation of the CES concept, which focuses on liver cases.
- Given a <u>query case with incomplete representation</u>, CaReRa searches and retrieves past cases relevant to the query case.
- CaReRa content analysis is <u>context-free</u> and is driven by an underlying ontology, user preferences and user relevance feedback.
- CaReRa (liver) case representation involves
  - Demographics
  - Clinical history (ICD-10 codes)
  - Drugs (ATC codes)
  - Laboratory results
  - Physical examination
  - Semantic radiological (CT) observations (ONLIRA ontology): UsE
  - Low-level image (CT) features: CoG



## imageCLEF: Liver CT Annotation Task

#### Motivation:

- The <u>query cases</u> in CaReRa are likely to be <u>incomplete</u> (missing the semantic UsE features).
- It has been shown that using semantic (UsE) features give a better retrieval perform than low-level computer generated CoG features.
- Prediction of UsE features from a given CT volume and/or CoG features is required to build a query for CaReRa.
- Besides, an automated semantic annotation using low-level computer generated features would be operational in <u>standardized</u> <u>radiology reporting and CAD systems</u>.

<sup>&</sup>lt;sup>1</sup> Neda Barzegar Marvasti, Ceyhun Burak Akgül, Burak Acar, Nadin Kökciyan, Suzan Üsküdarl, Pnar Yolum, Rüstü Türkay, and Bars Bakr, Clinical experience sharing by similar case retrieval, in Proceedings of the 1st ACM international workshop on Multimedia indexing and information retrieval for healthcare. ACM, 2013, pp. 6774



## Task definition and Datasets

#### Task definition:

Given a cropped CT volume enclosing the liver, the ONLIRA<sup>1</sup> ontology and a rich set of CoG features (for optional use), the task is to fill in a standardized radiology report that is composed of UsE features.

#### Datasets:

- 50 training and 10 test datasets.
- Each training dataset is represented as:
  - A cropped <u>CT volume</u> of the liver.
  - A <u>liver mask</u>, which defines liver in the image.
  - *ROI*, which defines lesion area in the image.
  - A set of <u>60 CoG image descriptors</u> of size 454.
  - A set of <u>73 UsE features</u> annotated using ONLIRA.
- Test sets has the same format but UsE features are missing, which are asked to be predicted.



## Computer generated features (CoG)

- CoG features describe the characteristics of liver, vessels and lesions of a CT image.
- Separated in two groups:
  - Global features (of size 93)

Group	Descriptor	Size
Liver	Volume Intensity mean and variance	3
Vessels	Volume Ratio in the liver	2
All lesions	Intensity mean and variance Number of lesions Volume of biggest and smallest lesions Ratio in the liver Histogram Histogram based features	88



# **Computer generated features (CoG)**

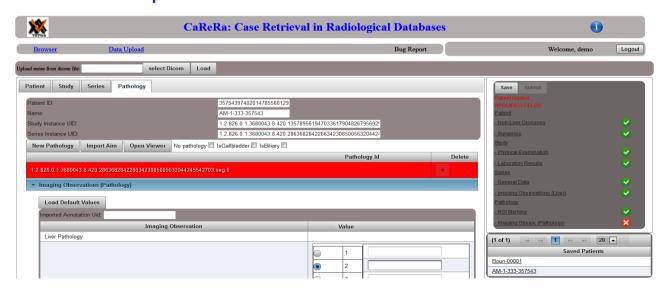
Individual features (of size 361)

Desc. Type	Desc. Name	Size
Geometric	Volume, area, sphericity, convexity, solidity, compactness, max. extent, aspect ratio	8
Locational	Anatomical location Convex area ratios Touch area ratio Proximity to vessels	5 2 1 1
Boundary	Scale, Window Fourier descriptor	33,3 3,20
GrayScale	Histogram Histogram based features	84
Texture	Haralick Tamura Gabor Hu moments	24 83 64 3

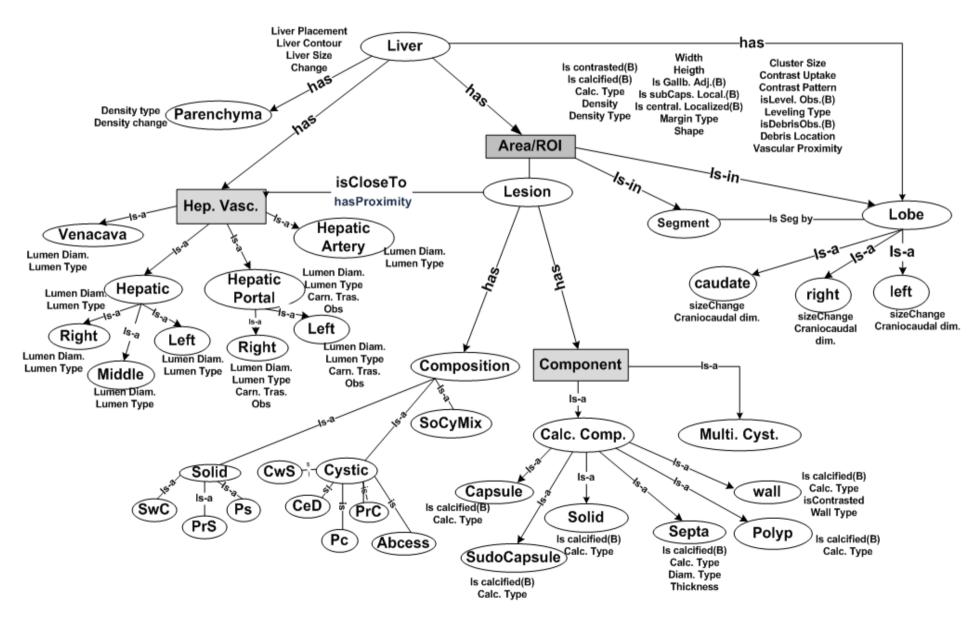


## **User expressed features (UsE)**

- ONLIRA (ONtology of the Liver for RAdiology) <sup>1</sup>
  - models the imaging observations of the liver domain.
  - represents properties and relationships between liver, hepatic veins and lesions.
- Imaging observations of a radiologist for the liver domain are represented with ONLIRA and collected in CaReRa-Web.
- CaReRa-Web is a web based data application which can be accessed at https://vavlab.ee.boun.edu.tr:5904/CareraWeb2









## **Evaluation methodology**

 Evaluation is based on <u>completeness and accuracy</u> of the predicted annotations with reference to the manual annotations of the test dataset.

$$Completeness = \frac{\text{number of predicted UsE features}}{\text{total number of UsE features}}$$

$$\text{number of predicted UsE features}$$

$$Accuracy = \frac{\text{number of predicted UsE features}}{\text{total number of predicted UsE features}}$$

- For answers, which allow multiple values to a question, the correct prediction of a single value is considered as the correct annotation.
- 7 out of 73 UsE features were excluded from the evaluation due to their unbounded labels(numeric continuous values).



- 20 groups registered, however 3 of them submitted their results.
- The number of runs per group was limited to ten.

Group name	Affiliation	runs
BMET	University of Sydney, Australia	8
CASMIP	The Hebrew University of Jerusalem, Israel	1
piLab	Bogaziçi University, Turkey	1

- BMET group, achieved the best results using an image retrieval technique with total score of 0.947.
- A classifier-based method was employed by CASMIP group.
- piLab used a Generalized couple tensor factorization (GCTF) method.



- They submitted 8 runs:
  - 4 using classier-based approach (RBF and linear kernels)
  - 4 using image retrieval algorithm (with feature selection, without feature selection)
- Experiments with 2 different feature sets:
  - CoG features
  - CoG features and bag of visual words (BoVW)
- The best result is achieved in the experiments with an image retrieval approach and by using the CoG features only.

<sup>1:</sup> Ashnil Kumar, Shane Dyer, Changyang Li, Philip H. W. Leong, and Jinman Kim, Automatic annotation of liver ct images: the submission of the bmet group to imageclefmed 2014, in CLEF 2014 Labs and Workshops, Notebook Papers. CEUR Workshop Proceedings (CEUR-WS.org), September 2014.



- In Classifier-based approach
  - They used 2-stage support vector machine (SVM) classification to annotate every UsE feature.
  - 1st stage is done using 1-vs-all SVM classifier.
  - 2<sup>nd</sup> stage is done using 1-vs-1 SVM classifier.
- 2<sup>nd</sup> stage is activated if the result of 1<sup>st</sup> step is more than one label, which is applied to the results of 1<sup>st</sup> step followed by a majority voting.
- This approach is employed using two different kernels and on two different feature sets.



- In image retrieval based approach
  - The most similar images from the training set to the current image are selected.
  - Then, a weighted voting scheme is applied to assign labels to each of the UsE features.
  - Similarity measure is defined as Euclidean distance.
- A sequential feature selection method is applied to use the most distinct features for each question during the similarity calculation.
- This approach is done with and without feature selection on two different feature sets.



Group	Run	Completeness	Accuracy	Score	Method	Feature
BMET	1	0.98	0.89	0.935	SVM-linear	CoG
BMET	2	0.98	0.90	0.939	SVM-linear	CoG+
BMET	3	0.98	0.89	0.933	SVM-RBF	CoG
BMET	4	0.98	0.90	0.939	SVM-RBF	CoG+
BMET	5	0.98	0.91	0.947	IR-noFS	CoG
BMET	6	0.98	0.87	0.927	IR-noFS	CoG+
BMET	7	0.98	0.91	0.947	IR-FS	CoG
BMET	8	0.98	0.87	0.926	IR-FS	CoG+



- They achieved the 2<sup>nd</sup> best performance.
- They tried 4 different classifiers in the learning phase:
  - Linear discriminant analysis (LDA)
  - Logistic regression (LR)
  - K-nearest neighbors (KNN)
  - SVM
- In learning phase, for every UsE feature the best classifier and CoG feature sets are learned via leave-one-out cross validation method.
- CoG features with dimensionality more than one are ignored, which reduces the number of employed CoG features to 39.

<sup>1:</sup> Assaf B. Spanier and Leo Joskowicz, Towards content-based image retrieval: From computer generated features to semantic descriptions of liver ct scans, in CLEF 2014 Labs and Workshops, Notebook Papers. CEUR Workshop Proceedings (CEUR-WS.org), September 2014.



- Nine additional low level image features describing the gray level properties of liver and lesion and also boundary properties of the lesion are used.
- Three UsE features including: cluster size, segment and lobe were extracted directly from the image features.
- For most of UsE features, they observed the same performance using any classifier and any combination of CoG features.
- For 6 of them related to density, contrast and location of the lesion, one of the LDA or KNN is chosen with their selected features.

Group	Run	Completeness	Accuracy	Score	Method	Feature
CASMIP	1	0.95	0.91	0.93	LDA + KNN	CoG+



- They considered the dataset as a heterogeneous data and applied coupled matrix factorization models using GCTF framework.
- Both KL divergence and Euclidean distance based cost functions are applied.
- They considered two groups of UsE features: the 1<sup>st</sup> group includes UsE features, which have values vary from 0 to 3 and the 2<sup>nd</sup> group contains UsE features that have binary values.
- Following matrices are provided:
  - X1: UsE features of first group(60\*21)
  - X2: UsE features of second group (60\*13)
  - Z1: CoG features (60\*447)

<sup>1:</sup> Beyza Ermis and A. Taylan Cemgil, Liver ct annotation via generalized coupled tensor factorization, in CLEF 2014 Labs and Workshops, Notebook Papers. CEUR Workshop Proceedings (CEUR-WS.org), September 2014.



Then the latent matrices Z2 and Z3 are estimated as:

$$X1 = Z1*Z2$$

$$X1 = Z1*Z2$$
  $X2 = Z1*Z3$ 

- The UsE features of test cases can be predicted using Z2 and Z3 via GCTF.
- Since the predicted values are not discrete values, a binary thresholding is applied.
- This group submitted three runs:

Group	Run	Completeness	Accuracy	Score	Method	Feature
piLab	1	0.51	0.39	0.45	GCTF-KL	CoG
piLab	2	0.51	0.89	0.677	GCTF-EUC	CoG
piLab	3	0.51	0.88	0.676	GCTF-KL	CoG



- The BMET group achieved the highest score with completeness of %98.
- In terms of accuracy, BMET group has also attained the best performance by using an image retrieval method.
- In terms of classier-based methods, BMET and CASMIP groups both obtained the total score of %93.

Group	Completeness	Accuracy	Score	Method	Feature
BMET	0.98	0.91	0.947	Image Retrieval	CoG
CASMIP	0.95	0.91	0.93	LDA + KNN	CoG+
piLab	0.51	0.89	0.677	GCTF	CoG



Results of different runs in predicting different groups of UsE features are as:

Group	Liver		Ves	sel		ion- ea	Lesi Les		Lesi Comp	
	Cmp.	Acc	Cmp	Acc	Cmp.	Acc	Cmp.	Acc	Cmp	Acc
BMET	1.00	0.93	1.00	1.00	0.92	0.79	1.00	0.83	1.00	0.94
CASMIP	1.00	0.93	1.00	1.00	0.85	0.81	0.90	0.82	1.00	0.94
piLab	0.62	0.88	1.00	1.00	0.46	0.77	0.20	1.00	0.12	0.15



- Results show that all groups have completed the vessel UsE features with high accuracy.
- The BMET and CASMIP groups completed liver features in full with accuracy more than %80.
- None of the groups can completely annotate the concepts related to lesion-area.
- Concepts related to lesion-components are fully completed and annotated with accuracy higher than %72 by both BIMET and CASMIP groups.
- Concepts related to lesion-lesion are annotated completely by only BIMET group with accuracy more than %72.



- This was the first time that liver CT annotation task was proposed.
- The challenge was to predict UsE features of patient records, given the CoG features.
- The main challenge of the task was due to the unbalanced dataset. Participants tried to overcome this issue with different methods.
- Among all methods, image retrieval scored the best performance.
- It was observed that feature selection is important for the best performance of the prediction method.



# Thank you

Any question?